



Review on Object Tracking Based on Shot Clustering and Joint Colour Texture Histogram Method

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Abstract: Object tracking is the process of locating a moving object over time in video. It has a variety of uses, some of which are: human-computer interaction, security and surveillance, traffic management and video editing. Video tracking can be a time consuming process due to the amount of data that is contained in video. As an Addition of it further to the complexity is the possible need to use object recognition techniques for tracking. The proposed method will improve greatly the tracking accuracy and efficiency. An object tracking algorithm is proposed to be presented by using the joint color texture histogram to represent a target.

Keywords: Human-computer interaction, Security, Objects tracking, Joint color Texture, Histogram.

I. INTRODUCTION

Object tracking has importance in real time environment because it plays an important role in several applications such as *Security and surveillance* to identify suspicious activity of peoples in mob, providing better sense of security using available visual information, In *Medical therapy* to improve the quality of life for physically handicapped patients, In banking industries to analyze behaviour of customers in bank during transactions, Traffic management on metro cities to analyze flow of traffic, and reductions of accidents. Video scene segmentation provides the most efficient solution so far. However, to proceed with scene segmentation, we will first apply low level segmentation of the video [4]. In various tracking algorithms used by different authors, mean shift tracking algorithms become popular because of their simplicity and efficiency. Furthermore, mean shift is a low complexity algorithm, which provides reliable solution for object tracking. Video is made up of number of capture moments that smallest part of video is called as shots, which is sequence of frames recorded by same camera. The visual content of video can be distributed by one or multiple frames, called key-frames. The number of key-frames we cannot determine previously because due to content variation it may be different for each shot [1]. Currently, it is found that a most of target representation algorithms are on the basis of object color, where which could be viewed as the discrete probability density function (PDF) of the target area. Color histogram is an efficient part of point sample distribution and is very proper in representing the dedicated object appearance. The background color patterns, which may be same for both object and foreground texture of the object, are the important features plays role to represent and recognize objects. Since background color pattern place new information that the object color histogram does not provide, using the joint color-texture histogram for target representation is simplest than using only color histogram or only texture histogram in targeted object tracking.

The proposed target representation scheme will eliminates similar color texture of background and reduces noise in the tracking process. Proceeding further towards the goal of object tracking and retrieval requires the grouping of shots into scenes. A scene can be called as a simultaneous series of semantically correlated shots of same video. The term scene usually refers to as a group of shots taken in the same physical location describing objects. A more accurate representation of a video could be the merging of scenes into some logical story units that corresponds to chapters describing the different subthemes of a movie.

Several approaches have been used by different authors for the scene segmentation and Object Tracking in the frames problem. Proposed work transforms this task into a color-texture problem of targeted object. A shot similarity graph proposed to be constructed, where each node represents a shot and the edges between shots will show their similarity based on color and motion information. Then the normalized cuts method proposed to be applying to partition this graph. In the method proposed for detecting boundaries of the logical story units by linking similar shots to each other and connecting overlapping links. For each shot, all key frames will cascade into a larger image and the similarity between shots will be computed by comparing these shot images. A scene transition graph proposed to be constructed to represent the video and the connectivity between shots. Then, this transition graph will be divided into connected sub graphs representing the scenes.

II. LITERATURE REVIEW & RELATED WORK

To achieve the objective, the surveyed literature is as mentioned.

Vasileios T. Chasanis, Aristidis C. Likas, and Nikolaos P. Galatsanos, proposed an algorithm in the area of video indexing, which require the efficient segmentation of video into scenes. They use typical scene detection algorithms [1].

Yun Zhai, Student and Mubarak Shah, proposed the videos, Consist of many consecutive shots that are captured by different camera operations, e.g., on/off operations and switching between cameras [2].

Jiafu Jiang And Hui Xiongin, Proposed Traditional color histogram Mean-shift (MS)algorithm & had considered only object's color statistical information, and didn't contain object's space information, so when the targeted object's color distribution was similar to the background texture, the traditional algorithms easily caused object tracking get inaccurate result or lost [3].

III. PROBLEM IN EXISTING METHODOLOGY

Color is a powerful feature for object tracking, using only color features is sufficient for most tracking tasks, However problems arise when the targeted object and background have similar color distribution.

That time it may be difficult to distinguish the object from background. So during object tracking we may get inaccurate result. As an improvement in above designed methodology our approach is mainly too focused on both color and background texture. Existing methods use temporal distance between shots in the definition of the similarity matrix that is subsequently used as input to the clustering procedure. Joint color texture histogram is decided to use to solve the difficulty of object color close to background color.

IV. PROPOSED WORK

- A. **Image segmentation:** The frames that we will extract from the available video that we will have are segmented first, then features of each object in the segmented image will extract, after that pattern matching is done on the simultaneously moving frames having the desired features in hand, the motion vectors will calculate and mask will moved accordingly.
- B. **Types of shots:** Important thing with any video is that it is made up of number of combinations of shots (*The consecutive frames from the beginning to the end of recording in a camera are called shot [9].*). Combining shots together will form a different scene and different scenes together form a total video. Shot shows a continuous action in an image sequence (*i.e. Frames*).
- C. **Key Frame Extraction:** For finding a KEY frame from video, first we will take frame of each shot as reference frame and all other frames within shots are general frames. After that we will compute the difference between all the general frames and reference frame in each shot with proposed algorithm. Then search for the maximum difference within a shot by using relation:

$$\text{Max}(i) = \{D_f(1, k)\}, k=2, 3 \dots N.$$

Now if the $\text{Max}(i) > MD$, then the frame with the maximum difference is called a key frame and otherwise with respect to the odd number of a shot's frames, the frame in the middle of shot is chose as key frame; in the case of the even number, any one frame between the two frames in the middle of shot can be chose as key frame [10].

V. METHODOLOGY

The main steps of our method can be depicted by the diagram as shown below.

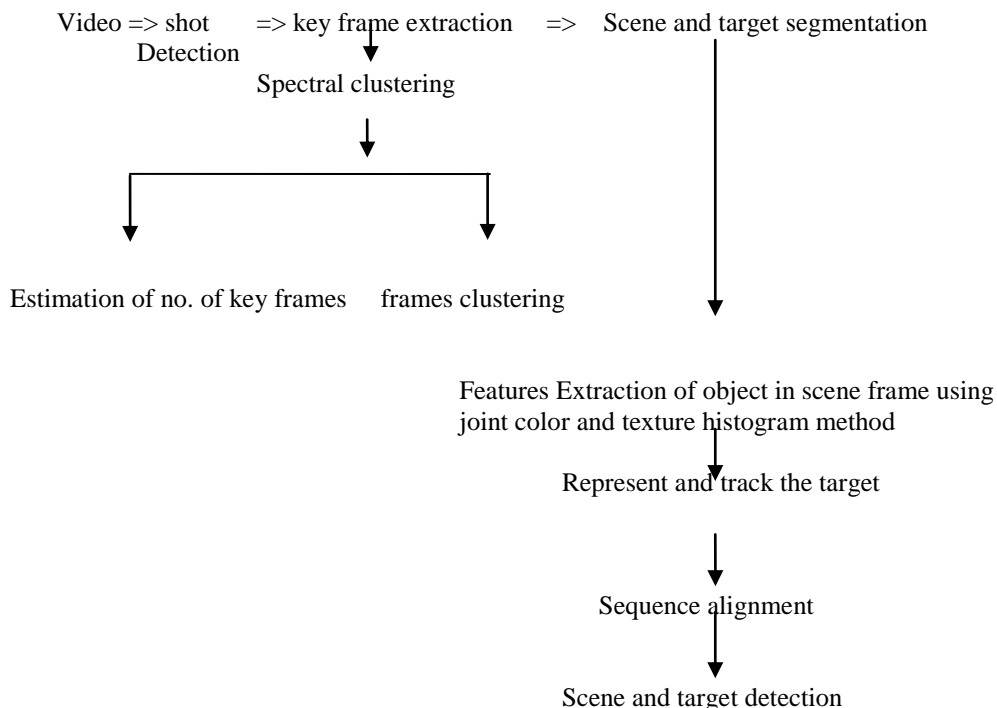


Fig. 1. Flow Chart of Complete System

VI. CONCLUSION AND FUTURE WORK

This paper gives an idea about the basic methods of moving object tracking in a video. It is somehow possible to give accurate result but problem arises when the target object and background have similar color distribution. It may be difficult to distinguish the object from background. So our future research on this topic is to implement a new method for object tracking, so that this problem will be eliminated.

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