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# Implementation of Approximations Algorithms with Simulated Annealing (SA)

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Abstract- Simulated annealing is a method of finding optimal values numerically. It chooses a new point, and (for optimization) all uphill points are accepted while some downhill points are accepted depending on probabilistic criteria. For certain problems, simulated annealing may be more efficient than exhaustive enumeration — provided that the goal is to find an acceptably good solution in a fixed amount of time, rather than the best possible solution. Simulated Annealing is a local search method based on local optimization. In this method each trial solution in the solution space has a cost, and the objective is to find a feasible solution of least cost. The method is iterative. In each cycle we try to move from the current trial solution S to a neighboring point S' in the solution space in an effort to find a better trial solution. Let us assume that the problem is a minimization problem. If cost(S') < cost(S), S' becomes the new trial solution; the move from S to S' is then called a downhill move. If cost(S') > cost(S), S' becomes the new trial solution with probability  $p = \exp(-\Delta/temp)$ , where temp is a parameter known as the temperature and  $\Delta = \cos(S')$ - cost(S); S is retained as the trial solution with probability (1-p). Thus S' can become the new trial solution even when its cost is higher than the cost of the current trial solution S; this kind of move from S to S' is called an uphill move. This deliberate choice of an inferior trial solution with a non-zero probability helps to ensure that the procedure does not get trapped in a local minimum. By slowly reducing the temperature, the probability p is reduced in the course of the iteration as better trial solutions are found. Bin packing problem [1], [2] solves the packing of objects of different volumes into a finite number of bins of capacity V in a way that minimizes the number of bins used. The approximation algorithm is applied on Multiple Bin Packing Problem in such a way that the algorithm produces the minimum number of bin used as a result.

Keyword- One bin packing, multiple bin packing, simulated annealing, best fit problem, first fit decreasing, metaheuristics, constraints (parameters).

#### 1. Introduction:

. This paper describes a complementary mechanism that attempts to learn the structure of the search space over multiple runs of SA on a given problem (Best fit Problem [6]) for one bin packing as well as Multiple Bin Packing. For this, we introduced different parameters for one bin packing and also for Multiple Bin Packing. Specifically, we also introduce a mechanism that attempts to predict how (un)-promising a SA run is likely to be, based on probability distributions that are "learned" over multiple runs. The distributions, which are built at different checkpoints, each corresponding to a different value of the temperature ('temperature' is a variable which decrements it's value at each step-as SA has a great relation with physics, the variable is termed in this manner) parameter used in the procedure, approximate the cost reductions that one can expect if the SA run is continued below these temperatures.

#### **II. Literature Review**

#### A. Bin Packing Problem-

The bin packing problem asks for the minimum number k of identical bins of capacity C needed to store a finite collection of weights  $w_1$ ,  $w_2$ ,  $w_3$ , ...,  $w_n$  so that no bin has weights stored in it whose sum exceeds the bin's capacity. Traditionally the capacity C is chosen to be 1 and the weights are real numbers which lie between 0 and 1, but here, for convenience of exposition, I will consider the situation where C is a positive integer and the weights are positive integers which are less than the capacity.

#### B. Simulated Annealing-

Simulated Annealing (SA) is a general-purpose search procedure that generalizes iterative improvement approaches to combinatorial optimization by sometimes accepting transitions to lower quality solutions to avoid getting trapped in local minima. SA procedures have been successfully applied to a variety of combinatorial optimization problems, including Traveling Salesman Problems ,Graph Partitioning Problems , Graph Coloring Problems[20], Vehicle Routing Problems[15] , Design of Integrated Circuits, Minimum Make-span Scheduling Problems as well as other complex scheduling problems, often producing near-optimal solutions, though at the expense of intensive computational efforts. The procedures, typically requiring that the procedure be rerun (iterate) a large number of times before a near optimal

solution are found. Other names of Simulated Annealing are Monte Carlo Annealing[5], Statistical Cooling[6], Probabilistic Hill Climbing[7], Stochastic Relaxation[9], Probabilistic Exchange Algorithm[8] etc.

C. Problem Definition-

The problem is categorized into two phases i.e., Phase I & Phase II

- 1) Phase I: The goal is to fit the different weighted objects into a single bin with the least cost function.
- 2) Phase II: The goal is to fit the different weighted objects into multiple bins such that minimum number of bins used.

#### III. Proposed Work:

A. Proposed Algorithm For Simulated Annealing:

```
Procedure SA
         input a trial solution S; c = cost(S); c^* = infinity; freezecount = 0; initialize temp;
         initialize frzlim, sizefactor, tempfactor, minpercent, tcent;
         while (freezecount < frzlim)
{
                  changes = trials = 0;
                  while (trials < sizefactor * N)
         /* N is determined by the size of the problem */
                            trials = trials + 1; generate a random neighbour S' of S;
                            c' = cost(S'); \Delta = c' - c;
                            if (S' is feasible and cost(S') < c^*)
                  S^* = S'; c^* = cost(S');
                            /* save best feasible solution found so far */
                            if (\Delta < 0)
                                      changes = changes + 1; c = c'; S = S';
         /* downhill move */
}
         /* possible uphill move */
                                     choose a random number r in [0,1];
                                     if ( r \le \exp(-\Delta/temp) )
{
                                               changes = changes+1; c = c'; S = S';
                                      }
         }
}
                  if (changes/trials > tcent) temp = 0.5 * temp;
                                                                            /* reduce temperature quickly */
                  else temp = tempfactor * temp;
                                                      /* reduce temperature slowly */
                            if ( changes/trials < minpercent ) freezecount = freezecount+1;</pre>
                  else freezecount = 0;
         output the final solution S*;
                                              /* S* is a feasible solution of minimum cost */
}
```

#### IV. Results Analysis:

A. For One Bin packing-

B. Table 1: Stress-Testing One Bin Packing NP hard Problem with Simulated Annealing

Target	Running-ONE-Bin-Packing-Approximation-Problem-utilizing-SimulatedAnnealing-with-									Differe	
(T): To		Trials(frzlim*trialLimit)									ntial
reach	Round	Round	Roun	Roun	Round	Round	Roun	Roun	Round	Average	Error:
MaxBin	_1:	_2:	d_3:	d_4:	_5:	_6:	d_7:	d_8:	_9:	BinSize	Absolut
Size	Trials	Trials	Trials	Trials	Trials	Trials	Trials	Trials	Trials	Reached	e Value
	=25	=	=100	=200	=	=	=1600	=	=	<b>(T)</b>	of (T`-
		50			400	800		3200	6400		T)/T
	frzlim	frzlim	frzlim	frzlim	frzlim	frzlim	frzlim	frzlim	frzlim		
	=5;Tri	=10;	=20;	=40;	=80;	=160;	=320;	=640;	=1200;		
	alLimt	TrialLi	Trial	Trial	TrialLi	TrialLi	Trial	Trial	TrialLi		
	=5	mit=5	Limit	Limit	mit=5	mit=5	Limit	Limit	mit=5		

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									o tille	2010, pp. 1	
			=5	=5			=5	=5			
100	95	99	82	100	72	98	100	91	99	93	0.07
300	300	300	300	299	300	300	300	300	300	300	0
900	884	897	899	900	884	900	900	900	900	896	0.00444
2700	2684	2696	2576	2698	2694	2696	2699	2700	2700	2683	0.00629
8100	7927	8063	8024	8097	8093	8100	8100	8099	8100	8067	0.00407 4
24300	24012	24154	24219	24187	24199	24230	24259	24279	24178	24191	0.00448 5
72900	70912	71861	72454	72865	72756	72888	72565	72701	72876	72431	0.00643
218700	217772	216438	21579 2	21675 4	214778	217865	21720	21682 0	213820	216373	0.01064

C. Analysis of Approximation Algorithm:

D. Table 2: Analysis of Approximation Algorithm

	FIRST-FI	Γ Algorithn	n	Analysis of Approximation Algorithms						
Trials	MaxBi n Size	Max Object Numbe r	Minimu m Number of Bin Require d(OPT)	BFD/FF D::Boun d is :: 11/9 OPT + 1 bins	Speciality Case :: FFD bound is tight :: 11/9 OPT + 6/9 bins	Modified Bin Packing (MFFD):: 71/60 OPT +1 bins	Bound 1 :: MFFD is bounded by 1.18 OPT	Bound2 :: 1.22 OPT for FFD	Tight Upper Bound for FF:: 17/10 OPT bins (Recent 2013)	
Round 1	10	6	4	5.888889	5.5555555	5.7333333	4.72	4.888	6.8	
Round 2	20	12	6	8.333332	7.99999999	8.0999998	7.08	7.32	10.2	
Round 3	40	24	12	15.66664	15.3333333	15.199996	14.16	14.64	20.4	
Round 4	80	48	24	30.33338	29.9999994	29.399992	28.32	29.28	40.8	
Round 5	160	96	48	59.66666	59.3333322	57.799998	56.64	58.56	81.6	
Round 6	320	192	96	118.3331	117.999997	114.59999	113.28	117.12	163.2	
Round 7	640	384	192	235.6662	235.33329	228.19993	226.56	234.24	326.4	
Round 8	1280	768	384	470.3332	469.999984	455.39999	453.12	468.48	652.8	

E. For Multiple Bin packing:

Table 3: Resultant Data

ruote 3. Resultant Bata							
Trials	Max Bin Size	Max Object Number	Minimum number of Bin Required (OPT)				
Round 1	10	6	4				
Round 2	20	12	6				

Round 3	40	24	12
Round 4	80	48	24
Round 5	160	96	48
Round 6	320	192	96
Round 7	640	384	192
Round 8	1280	768	384

**Table3: Work in Jan 2013 [27]** 

Trials	Max Bin Size	Max Object Number	Minimum number of Bin Required (OPT)
Round 1	10	6	6.8
Round 2	20	12	10.2
Round 3	40	24	20.4
Round 4	80	48	40.8
Round 5	160	96	81.6
Round 6	320	192	163.2
Round 7	640	384	326.4
Round 8	1280	768	652.8

### **SERIES 2**

Maximum Object Number & Minimum Number of Bin Required in this proposed work.

### **SERIES 1**

Maximum Object Number & Minimum Number of Bin in 2013

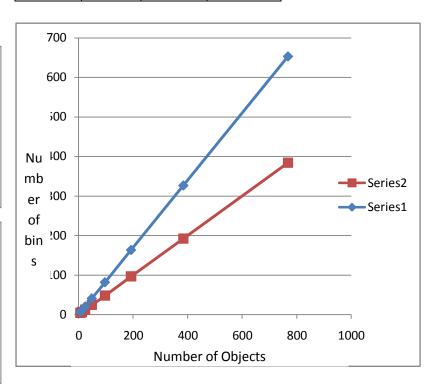


Figure 1: Comparison plot of Resultant data.

#### V. Conclusions:

Our work has been accomplished on a single bin of variable sizes with the implementation of simulated annealing on that particular bin with least runtime complexity. We have also accomplished our work on multiple bins of variable sizes with the implementation of simulated annealing with minimum number of bins used. A future aspect is to implement the above problems of 1bin packing as well as multiple bin packing in a 2-dimensional pattern.

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